

# **3-CATEGORIES, 3-GROUPS, AND UNIFICATION OF GRAVITY AND MATTER**

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# TOPICS

- Introduction
- Category theory and 3-groups
- Lie 3-groups
- Higher gauge theories
- The Standard Model
- Conclusions

# INTRODUCTION

## **The line of development that leads to higher gauge theories:**

- Within the LQG framework, the covariant quantization program is based on a “path integral on a lattice” idea, starting from the classical action for GR in the form of a  $BF$  theory with a simplicity constraint, known as the Plebanski action. The lattice quantization gives rise to spinfoam models.
- Since the Plebanski action does not contain the tetrad fields in its topological  $BF$  sector, the spinfoam models are hard to couple to matter fields. This problem is solved by passing to the  $2BF$  action, which is a categorical generalization of the  $BF$  theory. The matter fields can now be coupled, albeit in an ad hoc way (as in the Standard Model). The  $2BF$  action was a first physically relevant example of a higher gauge theory, and its lattice quantization was termed “spincube model”.
- Yet another categorical generalization to the new  $3BF$  action manages to combine gravity, gauge fields and matter fields in a unified geometric and algebraic way, paving the way to a “categorical unification” of all fields.

# CATEGORY THEORY AND 3-GROUPS

**A flash introduction to the category theory “ladder”:**

- a category  $\mathcal{C} = (Obj, Mor)$  is a structure which has objects and morphisms between them,

$$X, Y, Z, \dots \in Obj, \quad f, g, h, \dots \in Mor,$$

$$f : X \rightarrow Y, \quad g : Z \rightarrow X, \quad h : X \rightarrow Y, \dots$$

such that certain rules are respected, like the associativity of morphism composition, etc.

- a 2-category  $\mathcal{C}_2 = (Obj, Mor_1, Mor_2)$  is a structure which has objects, morphisms between them, and morphisms between morphisms, called 2-morphisms,

$$X, Y, Z, \dots \in Obj, \quad f, g, h, \dots \in Mor_1, \quad \alpha, \beta, \dots \in Mor_2,$$

$$f : X \rightarrow Y, \quad g : Z \rightarrow X, \quad h : X \rightarrow Y, \dots \quad \alpha : f \rightarrow h, \dots$$

such that similar rules as above are respected.

# CATEGORY THEORY AND 3-GROUPS

- a 3-category  $\mathcal{C}_3 = (Obj, Mor_1, Mor_2, Mor_3)$  additionally has morphisms between 2-morphisms, called 3-morphisms,

$$\Theta, \Phi, \dots \in Mor_3, \quad \Theta : \alpha \rightarrow \beta, \dots$$

again with a certain set of axioms about compositions of various  $n$ -morphisms.

- one can further generalize these structures to introduce 4-categories,  $n$ -categories,  $\infty$ -categories, etc.

## **The algebraic structure of a group is a special case of a category:**

- a group is a category with only one object, while all morphisms are invertible;
- a 2-group is a 2-category with only one object, while all 1-morphisms and 2-morphisms are invertible;
- a 3-group is a 3-category with only one object, while all 1-morphisms, 2-morphisms and 3-morphisms are invertible.

# LIE 3-GROUPS

A more practical way to talk about 3-group — a 2-crossed module:

$$L \xrightarrow{\delta} H \xrightarrow{\partial} G,$$

- for our purposes  $L$ ,  $H$  and  $G$  are ordinary Lie groups,
- there are two “boundary homomorphisms”  $\delta$  and  $\partial$ ,
- there is a defined action  $\triangleright$  of  $G$  onto  $G$ ,  $H$  and  $L$ ,

$$\triangleright : G \times G \rightarrow G, \quad \triangleright : G \times H \rightarrow H, \quad \triangleright : G \times L \rightarrow L,$$

- there is a bracket operation over  $H$  to  $L$ ,

$$\{ \ , \ } : H \times H \rightarrow L,$$

- and certain axioms are assumed to hold true among all these maps.

# LIE 3-GROUPS

The axioms of a 2-crossed module  $L \xrightarrow{\delta} H \xrightarrow{\partial} G$ :

$$g \triangleright \partial h = \partial(g \triangleright h),$$

$$g \triangleright \delta l = \delta(g \triangleright l),$$

$$g \triangleright g_0 = g g_0 g^{-1},$$

$$g \triangleright \{h_1, h_2\} = \{g \triangleright h_1, g \triangleright h_2\},$$

$$\partial \delta = 1_G,$$

$$\delta \{h_1, h_2\} = h_1 h_2 h_1^{-1} (\partial h_1) \triangleright h_2^{-1},$$

$$\{\delta l_1, \delta l_2\} = l_1 l_2 l_1^{-1} l_2^{-1},$$

$$\{h_1 h_2, h_3\} = \{h_1, h_2 h_3 h_2^{-1}\} \partial h_1 \triangleright \{h_2, h_3\},$$

$$\{\delta l, h\} \{h, \delta l\} = l(\partial h \triangleright l^{-1}).$$

... for all  $g \in G$ ,  $h \in H$  and  $l \in L$ ... :-)

# LIE 3-GROUPS

A Lie 3-group has a corresponding Lie 3-algebra, i.e. a differential 2-crossed module:

$$\mathfrak{l} \xrightarrow{\delta} \mathfrak{h} \xrightarrow{\partial} \mathfrak{g},$$

- where  $\mathfrak{l}$ ,  $\mathfrak{h}$ ,  $\mathfrak{g}$  are Lie algebras of  $L$ ,  $H$ ,  $G$ ,
- the maps  $\delta$ ,  $\partial$ ,  $\triangleright$  and  $\{ \ , \ }$  are inherited from the 3-group,
- “corresponding” axioms apply.

In addition to all this, Lie algebras have their own Lie structure:

- generators,

$$T_A \in \mathfrak{l}, \quad t_a \in \mathfrak{h}, \quad \tau_\alpha \in \mathfrak{g}$$

- structure constants,

$$[T_A, T_B] = f_{AB}^C T_C, \quad [t_a, t_b] = f_{ab}^c t_c, \quad [\tau_\alpha, \tau_\beta] = f_{\alpha\beta}^\gamma \tau_\gamma,$$

- and symmetric bilinear invariant Killing forms,

$$\langle T_A, T_B \rangle_{\mathfrak{l}} = g_{AB}, \quad \langle t_a, t_b \rangle_{\mathfrak{h}} = g_{ab}, \quad \langle \tau_\alpha, \tau_\beta \rangle_{\mathfrak{g}} = g_{\alpha\beta}.$$

# LIE 3-GROUPS

The main purpose of all this structure is to generalize the notion of parallel transport from curves to surfaces to volumes:

- Given a 4-dimensional manifold  $\mathcal{M}$ , define a 3-connection  $(\alpha, \beta, \gamma)$  as a triple of 3-algebra-valued differential forms,

$$\begin{aligned}\alpha &= \alpha^\alpha{}_\mu(x) \tau_\alpha \mathbf{d}x^\mu && \in \Lambda^1(\mathcal{M}, \mathfrak{g}), \\ \beta &= \frac{1}{2} \beta^a{}_{\mu\nu}(x) t_a \mathbf{d}x^\mu \wedge \mathbf{d}x^\nu && \in \Lambda^2(\mathcal{M}, \mathfrak{h}), \\ \gamma &= \frac{1}{3!} \gamma^A{}_{\mu\nu\rho}(x) T_A \mathbf{d}x^\mu \wedge \mathbf{d}x^\nu \wedge \mathbf{d}x^\rho && \in \Lambda^3(\mathcal{M}, \mathfrak{l}).\end{aligned}$$

- Then introduce the line, surface and volume holonomies,

$$g = \mathcal{P} \exp \int_{\mathcal{C}_1} \alpha, \quad h = \mathcal{P} \exp \int_{\mathcal{S}_2} \beta, \quad l = \mathcal{P} \exp \int_{\mathcal{V}_3} \gamma,$$

- and corresponding curvature forms,

$$\begin{aligned}\mathcal{F} &= \mathbf{d}\alpha + \alpha \wedge \alpha - \partial\beta, \\ \mathcal{G} &= \mathbf{d}\beta + \alpha \wedge^\triangleright \beta - \delta\gamma, \\ \mathcal{H} &= \mathbf{d}\gamma + \alpha \wedge^\triangleright \gamma - \{\beta \wedge \beta\}.\end{aligned}$$

# HIGHER GAUGE THEORIES

At this point one can construct the so-called  $3BF$  theory, with the action:

$$S_{3BF} = \int_{\mathcal{M}} \langle B \wedge \mathcal{F} \rangle_{\mathfrak{g}} + \langle C \wedge \mathcal{G} \rangle_{\mathfrak{h}} + \langle D \wedge \mathcal{H} \rangle_{\mathfrak{l}}.$$

- $3BF$  theory is a topological gauge theory,
- it is based on the 3-group structure,
- it is a generalization of an ordinary  $BF$  theory for a given Lie group  $G$ ,

**The physical interpretation of the Lagrange multipliers  $C$  and  $D$ :**

- the  $\mathfrak{h}$ -valued 1-form  $C$  can be interpreted as the tetrad field, if  $H = \mathbb{R}^4$  is the spacetime translation group:

$$C \rightarrow e = e^a{}_{\mu}(x) t_a \mathbf{d}x^{\mu},$$

- the  $\mathfrak{l}$ -valued 0-form  $D$  can be interpreted as the set of real-valued matter fields, given some Lie group  $L$ :

$$D \rightarrow \phi = \phi^A(x) T_A.$$

# HIGHER GAUGE THEORIES

**How to choose the 3-group? The simplest example — the (trivial) Standard Model 3-group:**

$$G = SO(3, 1) \times SU(3) \times SU(2) \times U(1), \quad H = \mathbb{R}^4, \quad L \text{ to be discussed.}$$

- boundary maps are trivial — for all  $l \in L$  and  $\vec{v} \in H$ , we define

$$\delta l = 1_H = 0, \quad \partial \vec{v} = 1_G,$$

- the bracket is trivial — for all  $\vec{u}, \vec{v} \in H$ , we define

$$\{\vec{u}, \vec{v}\} = 1_L,$$

- the action  $\triangleright$  of  $G$  on itself is via the adjoint representation, the action on  $H$  is via vector representation for the  $SO(3, 1)$  sector and via trivial representation for the  $SU(3) \times SU(2) \times U(1)$  sector.
- the action of  $G$  on  $L$  is nontrivial and depends on the choice of  $L$  (to be discussed).

**One can verify that all axioms of a 3-group are satisfied.**

# HIGHER GAUGE THEORIES

How to choose  $L$ ? Study the  $3BF$  action:

$$S_{3BF} = \int_{\mathcal{M}} B^\alpha \wedge \mathcal{F}^\beta g_{\alpha\beta} + e^a \wedge \mathcal{G}^b g_{ab} + \phi^A \mathcal{H}^B g_{AB}.$$

- The indices  $\alpha$  of  $G$  split according to its structure, as  $\alpha = (ab, i)$ , giving the connection and curvature

$$\alpha = \omega^{ab} J_{ab} + A^i \tau_i, \quad \mathcal{F} = R^{ab} J_{ab} + F^i \tau_i.$$

- The vectorial action of  $SO(3, 1)$  on  $H = \mathbb{R}^4$  implies the Minkowski signature of the bilinear invariant on  $\mathbb{R}^4$ , so that

$$g_{ab} = \eta_{ab} \equiv \text{diag}(-1, +1, +1, +1).$$

- Given that  $\phi = \phi^A T_A$ , we have one real-valued field  $\phi^A(x)$  for each generator  $T_A \in \mathfrak{l}$ .

# THE STANDARD MODEL

How many real-valued field components do we have in the matter sector of the Standard Model? The fermion sector gives us:

$$\left. \begin{array}{cccc} \left( \begin{array}{c} \nu_e \\ e^- \end{array} \right)_L & \left( \begin{array}{c} u_r \\ d_r \end{array} \right)_L & \left( \begin{array}{c} u_g \\ d_g \end{array} \right)_L & \left( \begin{array}{c} u_b \\ d_b \end{array} \right)_L \\ \nu_e)_R & (u_r)_R & (u_g)_R & (u_b)_R \\ (e^-)_R & (d_r)_R & (d_g)_R & (d_b)_R \end{array} \right\} = 16 \frac{\text{spinors}}{\text{family}} \times$$

$$\times 3 \text{ families} \times 4 \frac{\text{real-valued fields}}{\text{spinor}} = 192 \text{ real-valued fields } \phi^A.$$

**The Higgs sector gives us:**

$$\left. \begin{array}{c} \phi^+ \\ \phi_0 \end{array} \right\} = 2 \text{ complex scalar fields} = 4 \text{ real-valued fields } \phi^A.$$

**This suggests the structure for  $L$  in the form:**

$$L = L_{\text{fermion}} \times L_{\text{Higgs}}, \quad \dim L_{\text{fermion}} = 192, \quad \dim L_{\text{Higgs}} = 4.$$

# THE STANDARD MODEL

The action  $\triangleright : G \times L \rightarrow L$  specifies the transformation properties of each real-valued field  $\phi^A$  with respect to Lorentz and internal symmetries.

- For example, in

$$\begin{pmatrix} u_b \\ d_b \end{pmatrix}_L$$

the action

$$g \triangleright u_b, \quad g \in SO(3, 1) \times SU(3) \times SU(2) \times U(1),$$

encodes that  $u_b$  consists of 4 real-valued fields which transform as:

- a left-handed spinor wrt.  $SO(3, 1)$ ,
  - as a “blue” component of the fundamental representation of  $SU(3)$ ,
  - and as “isospin  $+\frac{1}{2}$ ” of the left doublet wrt.  $SU(2) \times U(1)$ .
- Moreover,  $G$  acts in the same way across families, suggesting the structure

$$L_{\text{fermion}} = L_{\text{1st family}} \times L_{\text{2nd family}} \times L_{\text{3rd family}}, \quad \dim L_{k\text{-th family}} = 64.$$

# THE STANDARD MODEL

**A realisation that reproduces the Standard Model:**

- Choice of the 3-group:

$$L = \mathbb{R}^4(\mathbb{C}) \times \mathbb{R}^{64}(\mathbb{G}) \times \mathbb{R}^{64}(\mathbb{G}) \times \mathbb{R}^{64}(\mathbb{G}),$$

$$G = SO(3, 1) \times SU(3) \times SU(2) \times U(1), \quad H = \mathbb{R}^4,$$

where  $\mathbb{G}$  is the Grassmann algebra.

- The constrained  $3BF$  action:

$$\begin{aligned} S = & \int B_{\hat{\alpha}} \wedge \mathcal{F}^{\hat{\alpha}} + e_{\hat{a}} \wedge \mathcal{G}^{\hat{a}} + D_{\hat{A}} \wedge \mathcal{H}^{\hat{A}} \\ & + \left( B_{\hat{\alpha}} - C_{\hat{\alpha}}^{\hat{\beta}} M_{cd\hat{\beta}} e^c \wedge e^d \right) \wedge \lambda^{\hat{\alpha}} - \left( \gamma_{\hat{A}} - e^a \wedge e^b \wedge e^c C_{\hat{A}}^{\hat{B}} M_{abc\hat{B}} \right) \wedge \lambda^{\hat{A}} - 4\pi i l_p^2 \varepsilon_{abcd} e^a \wedge e^b \wedge \beta^c D_{\hat{A}} T^{d\hat{A}}_{\hat{B}} D^{\hat{B}} \\ & + \zeta^{ab}_{\hat{\alpha}} \wedge \left( M_{ab}^{\hat{\alpha}} \varepsilon^{cdef} e_c \wedge e_d \wedge e_e \wedge e_f - F^{\hat{\alpha}} \wedge e_c \wedge e_d \right) + \zeta^{ab}_{\hat{A}} \wedge \left( M_{abc}^{\hat{A}} \varepsilon^{cdef} e_d \wedge e_e \wedge e_f - F^{\hat{A}} \wedge e_a \wedge e_b \right) \\ & - \varepsilon_{abcd} e^a \wedge e^b \wedge e^c \wedge e^d \left( M_{\hat{A}\hat{B}} D^{\hat{A}} D^{\hat{B}} + Y_{\hat{A}\hat{B}\hat{C}} D^{\hat{A}} D^{\hat{B}} D^{\hat{C}} + L_{\hat{A}\hat{B}\hat{C}\hat{D}} D^{\hat{A}} D^{\hat{B}} D^{\hat{C}} D^{\hat{D}} \right). \end{aligned}$$

# CONCLUSIONS

- Higher gauge theory represents a formalism where gravity, gauge fields, fermions and Higgs are treated on an equal footing.
- The underlying algebraic structure of a 3-group classifies all fundamental fields by specifying groups  $L, H, G$  and their maps  $\delta, \partial, \triangleright, \{ , \}$ .
- This structure has natural geometrical interpretation of parallel transport along a curve, a surface, and a volume.
- The gauge group  $L$  specifies the complete matter sector of the Standard Model if one chooses

$$L = \mathbb{R}^4(\mathbb{C}) \times \mathbb{R}^{64}(\mathbb{G}) \times \mathbb{R}^{64}(\mathbb{G}) \times \mathbb{R}^{64}(\mathbb{G}).$$

- The action  $\triangleright$  of  $G$  on  $L$  specifies the transformation properties of matter fields.
- Nontrivial choices of the 3-group structure may provide new avenues for research on unification of all fields.

***THANK YOU!***